Then for small $C$ we expect that

$$
\begin{equation*}
u \approx C v \tag{9.4}
\end{equation*}
$$

We see in Figure 11.2 that this is the case.
In this case, we can go one step further since it is possible to solve (9.3) exactly:

$$
\begin{equation*}
v(\xi)=\frac{1}{4}-\frac{e^{-2(\theta-\xi)}+e^{2(\theta-\xi)}}{4\left(e^{-2 \theta}+e^{2 \theta}\right)} \tag{9.5}
\end{equation*}
$$

Therefore we can compute $\|u-C v\|_{L^{2}(\Omega)}$ to see if it goes to zero as $C \rightarrow 0$.
Thus there are useful tests that can be done for nonlinear problems that can determine whether or not the code is producing reasonable answers.

### 9.2.2 Nonlinear variational problems

We will introduce subsequently a problem whose variational formulation takes the form

$$
\begin{equation*}
a(u, v)+n(u, v)=(f, v)_{L^{2}([0,1])} \quad \forall v \in V \tag{9.6}
\end{equation*}
$$

where

$$
a(u, v)=\int_{0}^{\theta} u^{\prime}(x) v^{\prime}(x)+4 u(x) v(x) d x
$$

and the nonlinearity has been separated for convenience in the form

$$
\begin{equation*}
n(u, v)=6 \int_{0}^{\theta} u(x)^{2} v(x) d x=6\left(u^{2}, v\right)_{L^{2}([0,1])} \tag{9.7}
\end{equation*}
$$

Note that this is nonlinear in the trial function $u$ and linear in the test function $v$.
A Galerkin method for a space with a basis $\left\{\phi_{i}: i=1, \ldots, n\right\}$ can be written as a system of nonlinear equations

$$
\begin{equation*}
F_{i}(u):=a\left(u, \phi_{i}\right)+n\left(u, \phi_{i}\right)-\left(f, \phi_{i}\right)_{L^{2}([0,1])}=0 \tag{9.8}
\end{equation*}
$$

Writing $u=\sum_{j} U_{j} \phi_{j}$, Newton's method for this system of equations for $\left(U_{j}\right)$ can be derived. However, it can also be cast in variational form as follows.

Instead of using a basis function, let us define a function $F$ with coordinates parameterized by an arbitrary $v \in V$ :

$$
\begin{equation*}
F_{v}(u):=a(u, v)+n(u, v)-(f, v)_{L^{2}([0,1])} \tag{9.9}
\end{equation*}
$$

If $v=\phi_{i}$ then of course we have the previous function. Newton's method requires us to compute the derivative of $F$ with respect to its "coordinates" which in this case correspond to elements of $V$. The derivative of $F_{v}$ at $u$ in the direction of $w \in V$ is, as always, a limit of a difference quotient,

$$
\begin{equation*}
\frac{F_{v}(u+\epsilon w)-F_{v}(u)}{\epsilon} \tag{9.10}
\end{equation*}
$$

as $\epsilon \rightarrow 0$. Expanding, we find that

$$
\begin{align*}
F_{v}(u+\epsilon w)-F_{v}(u) & =\epsilon a(w, v)+6\left((u+\epsilon w)^{2}-u^{2}, v\right)_{L^{2}([0,1])}  \tag{9.11}\\
& =\epsilon a(w, v)+6\left(2 \epsilon u w+\epsilon^{2} w^{2}, v\right)_{L^{2}([0,1])}
\end{align*}
$$

